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Nonlinear Systems and Control (227-0207)

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Maëva Slotine. Maëva founded Slotine in 2016 after being admitted in Hong Kong, France, and England & Wales. Since beginning her career in 1998, she has gained extensive experience on numerous multinational cases globally, focusing on mergers and acquisitions, private equity transactions, foreign direct investments and corporate governance ...

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Nonlinear governing equations are constructed for both collocated and non-collocated force sensor configurations. The models take into account large time delays in the feedback loop, which may occur, for example, in case of human or remote force control. The corresponding stability charts are compared for the collocated and non-collocated cases.

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